

## with integrated process controller

**Compact digital positioner for pneumatic valves with integrated process controller.**

- Combination of positioner and process controller
- Compact solution for local control tasks
- Suitable for fast controlled systems
- Cycle time selectable between 25ms, 50ms, 100ms, 200ms and 500ms
- Internal or External setpoint specification
- Clearly legible display
- Sensor signal: Current interface and Pt100
- Can be configured as P-, PI-, PD- and PID-controller
- Integrated stroke feedback without exposed parts
- Big stroke range 3 - 28 / 3 - 50 mm
- Self learning adaption to valve actuator
- Configuration and diagnostic functions via PC software or directly on the display
- Not vulnerable to vibrations
- Protection class IP 65
- Also available for part turn actuators (single or double acting)



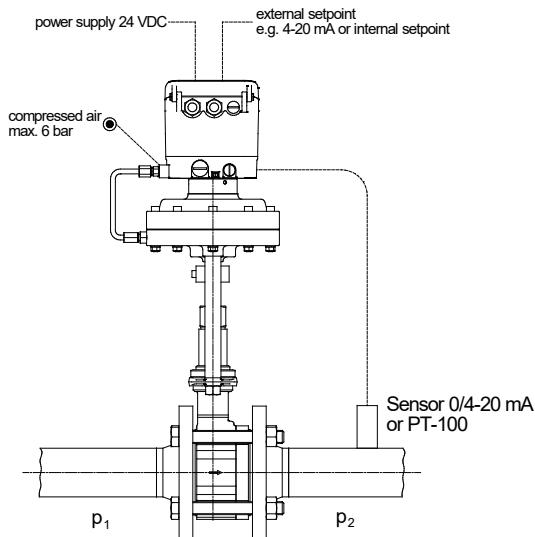
### Technical Information

nominal stroke	3 - 28 / 3 - 50 mm
voltage of the working resistance	2,5 V (125Ω@20mA)
ambient temperature	-10 up to +75°C
Control variable (actual value)	0/4 - 20 mA, PT100 (2 or 3-wire)
Reference variable (set point)	via keyboard or 0/4 - 20 mA, 0/2 - 10 V
Control behaviour	P (with working point y0) PD (with working point y0) PI PID
Accuracy	≤ 0,5% of the end value
Alarm output	absolut direct/invers, realtiv direct/invers, Band direct/invers
auxiliary energy, electric	24 VDC max. 10 W
adjustment of stroke and zero point	self-learning
configuration	Directly on the display or via PC software
auxiliary energy, pneumatic	max. 6 bar
unrestricted air capacity *	40 Nl/min
stationary air consumption *	< 0,06 Nl/min
Leakage	< 0,01 Nl/min
air quality according ISO 8573-1:	
max. particle size and density:	Class 5
oil content	Class 4
pressure dew point	Class 3
Actuation gas	min. 20K (36°F) under ambient temperature compressed air or non flammable gases (nitrogen, CO2,...)
mounting to control valve	standardized mounting kits (also with optical position indicator)
pressure supply port	G 1/8"
Max. Connection cross-section	1,5mm <sup>2</sup>
protection class acc. DIN 40050	IP 65

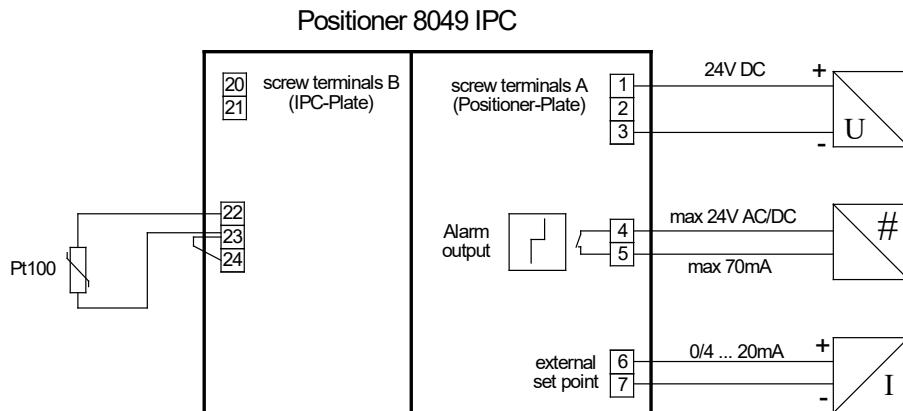
\* at 5 bar pilot pressure

## Functional description

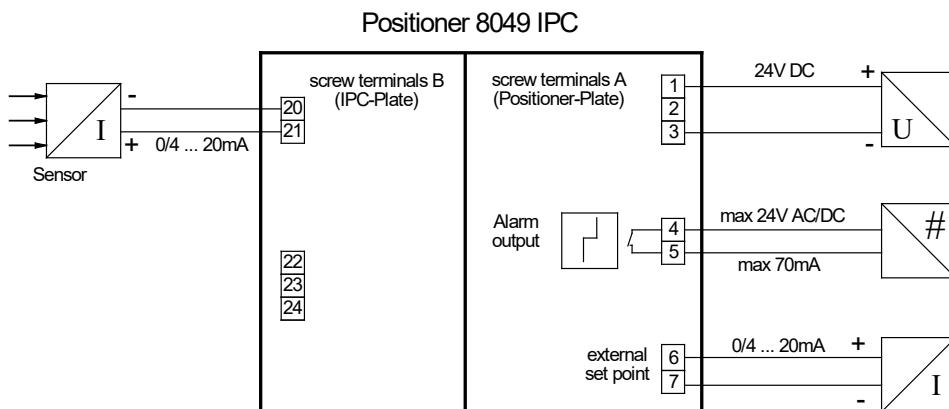
The 8049-IPC with integrated process controller offers a solution for demanding control tasks without higher-level process control systems. The basis of the 8049-IPC is the proven positioner 8049 in the 4-wire version. One additional IPC-module in the cover plate of the basic unit forms the complete unit of the 8049-IPC. The connection of a process sensor as reference variable, optionally as 0/4-20 mA sensor or PT-100 element, is made directly at the 8049-IPC. The setpoint can be specified either externally or directly on the controller display. Scaling of the 8049-IPC as a P, PI, PD or PID controller offers the optimum solution for every process, especially in combination with valve technology from Schubert & Salzer. The process-related control parameters can be set either directly on the 8049-IPC or via the software DeviceConfig. Based on the control parameters, the IPC module calculates the difference between the reverence variable and the setpoint. In parallel, the process controller supplies the positioner within a variable cycle time with the control signal required for positioning. Thus, each control difference results in a change of the valve stroke.



## Connection example Pt-100



## Connection example mA-sensor

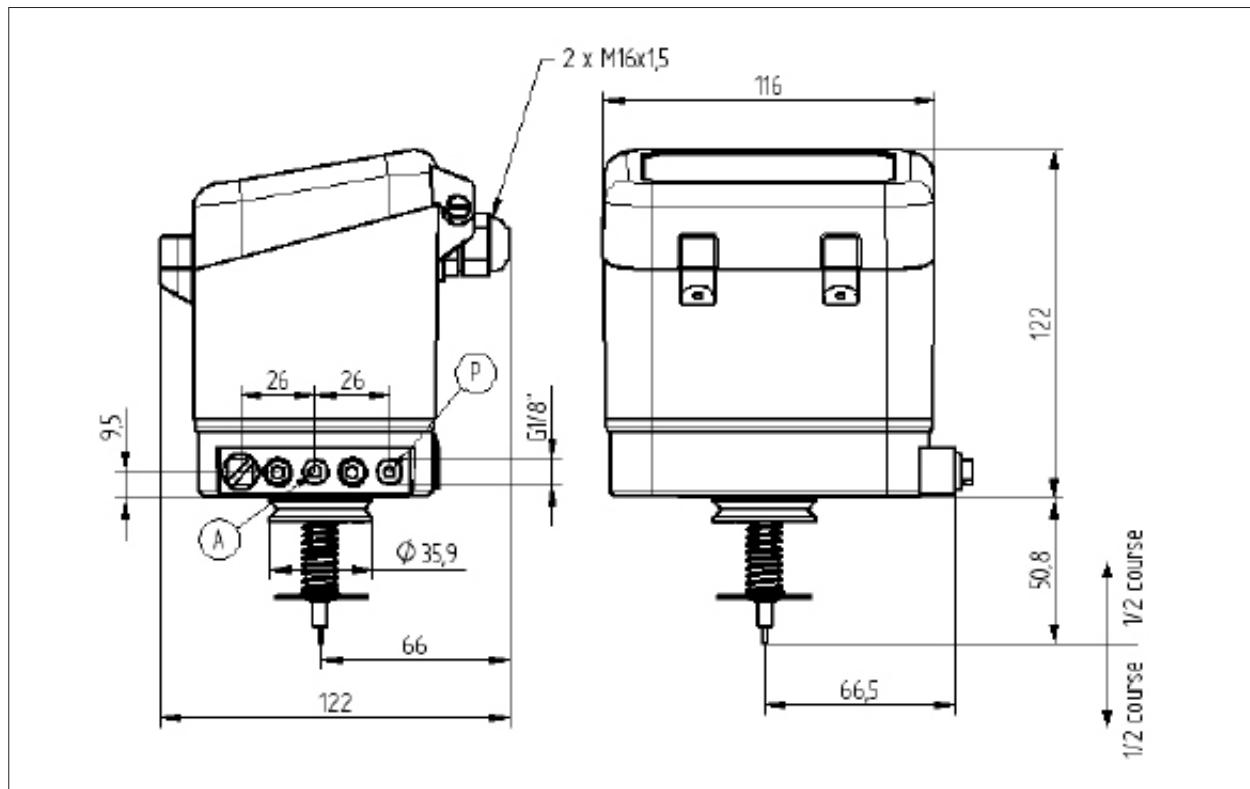


## Ordering number system

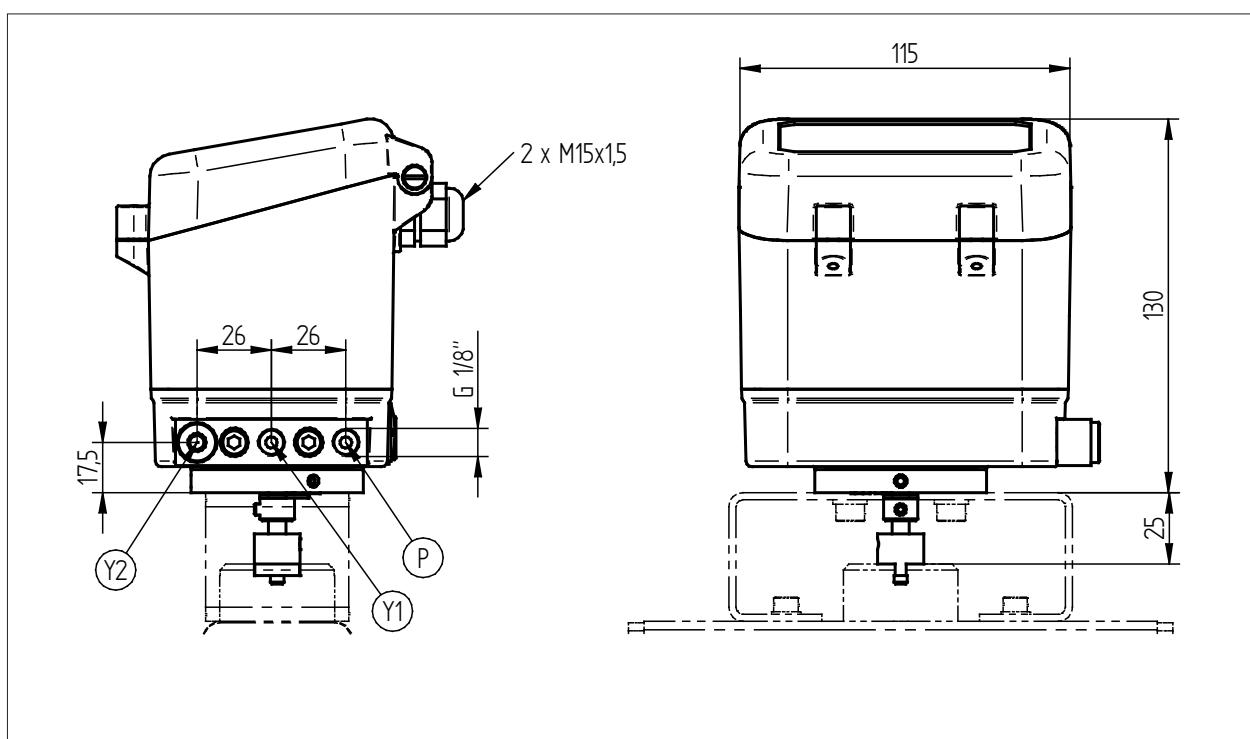
	quote only if required									
	8049/	-	-	-	-	-	-	-	S	-
Basic design										
dig. positioner 8049-4 (version 6)	4P6									
For acutator										
single acting		1								
double acting		2								
Air delivery										
standard			S							
high			H							
Body										
aluminium / plastic			0							
stainless steel ground plate			1							
body in stainless steel			2							
Electro-pneumatic connection										
Cable Bush 2 x M16x1,5 + 1 x M12x1,5			0							
NPT-thread 1/2"			1							
plug connection M12x1, 5-pin			2							
Pneumatic connection										
G 1/8"			0							
NPT 1/8"			1							
Position measuring										
linear potentiometer without sensing pin			0							
linear potentiometer with standard sensing pin (L=99,6mm)			1							
linear potentiometer with curtated sensing pin (L=94,4 mm)			G							
rotary potentiometer for semi-rotary drive			2							
EMV-galvanic separating module for exterior path sensor			3							
Optical indicator										
without indicator			0							
indicator disc for sensing pin in PA			1							
indicator disc for sensing pin in metal			2							
rotation angle indicator			3							
Auxiliary module										
without auxiliary module			0							
IPC-process controller			C							
Accessories										
without accessories			0							
manometer bloc single acting, scaling in bar and PSI			1							
optical position indicator for rotating actuators			2							
Further details										
special design (quote only if required)				S						
positioner montage (only for the manufacturer)				M						
Settings										
standard					-					
settings on customer request					1					
Special design										
without						-				
separated version incl. exterior path sensor for lift drive						1				

## Dimensions

**For linear actuators**



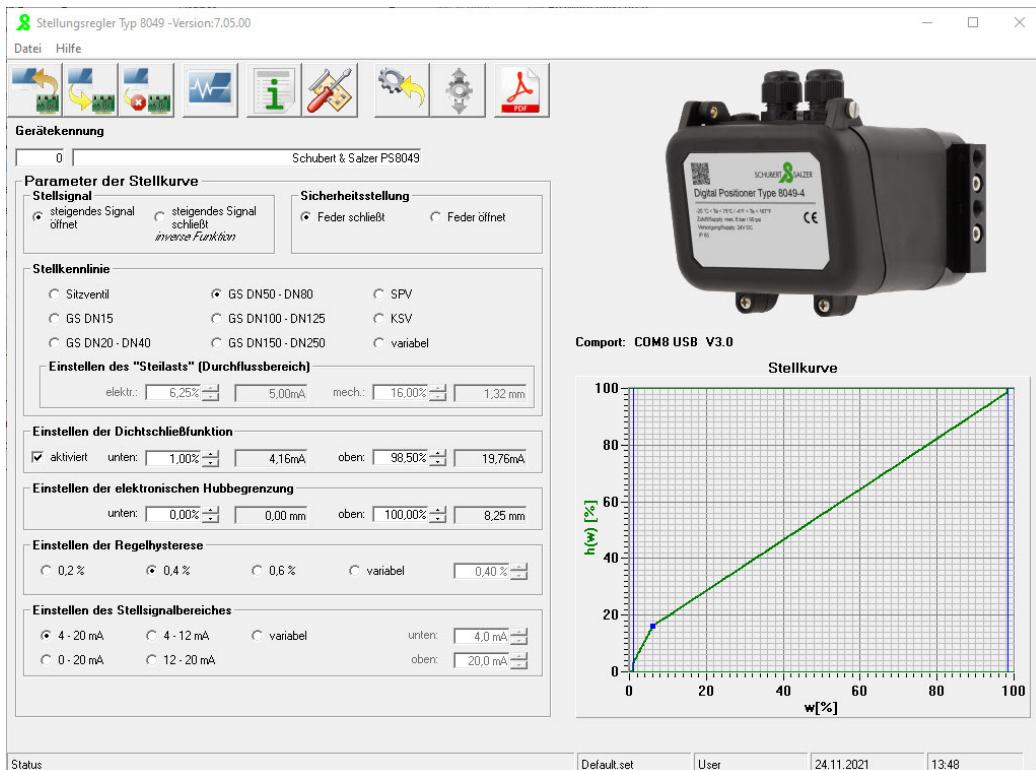
## For quarter-turn actuators



## Configuration-Software „DeviceConfig“

### Setup-Parameters

Adjustment of controlling parameters (input signal, stroke limitation, tight closing function, control hysteresis, valve function,...)



### Live-Monitor

The operating conditions of the positioner, can be viewed with the live monitor.



## Configuration-Software „DeviceConfig“

### Settings of the IPC-Modul

parametrisation of the IPC-module

IPC

Settings	Information	Monitor
<b>IPC settings</b>		
ALAr - alarm-setpoint value: <input type="text" value="0.50"/> HISI - alarm hysteresis <input type="text" value="0.10"/> In physical unit		
PASS - password <input type="text" value="1"/> Negative value = complete lock		
IPC <input checked="" type="radio" value="ON"/> ON <input type="radio" value="OFF"/> OFF		
InPu -source of actual value <input type="text" value="Pt - PT100"/>		
Sub-menu-USER -> →		
CtrL - control function <input type="radio" value="d - direct"/> d - direct <input checked="" type="radio" value="i - inverse"/> i - inverse		
SEIP - source of setpoint value <input type="text" value="0-20 ... 0.20 mA, extenal analog input"/>		
Internal setpoint value: <input type="text" value="123"/>		
IALr - Type of alarm <input type="text" value="AbHi - Alarm high (absolute value)"/>		
FILT - Filter: <input type="radio" value="ON"/> ON <input checked="" type="radio" value="OFF"/> OFF		
Sub-menu-PId -> →		
Mode: <input checked="" type="radio" value="Automatic mode"/> Automatic mode <input type="radio" value="Manual mode"/> Manual mode		
Only IPC extension		
<input type="button" value="Generate IPC PDF"/>	<input type="button" value="Load adjustments"/>	
<input type="button" value="Factory reset"/>	<input type="button" value="Save adjustments"/>	
<b>Sub-menu USER - scaling of input values</b>		
dEC - decimal points <input type="text" value="1"/>	0..2	
Lo - Lower setpoint value and actual value <input type="text" value="0,00"/>	In physical unit	
Hi - Upper setpoint value and actual value <input type="text" value="10,00"/>	In physical unit	
<b>Sub-menu- PId -controller parameter</b>		
bp -proportional range <input type="text" value="123,00 %"/>	1,0 .. 99,99%	
tn - integral time <input type="text" value="0sek"/>	1 .. 4999 sek ; 5000 = OFF	
td - derivative time <input type="text" value="0sek"/>	1 .. 2999 sek ; 0 = OFF	
y0 - operating point <input type="text" value="0 %"/>	0 .. 100% (only if tn = OFF)	
<input type="button" value="Back"/>		

### Diagnostic data

Informations of valve stroke,running time, soft- and hardware-versions, achieved temperature- and stroke levels, error messages, number of cycles, operating hours...

Diagnosis

Base	Version information	Temperature- /way classes	Status / Error	Maintenance	Diagnosis																																																																	
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